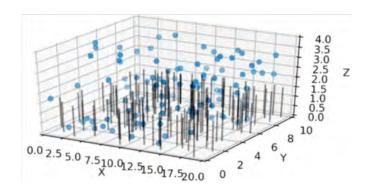
Modeling Movement and Persistence of Small Organisms in Flow



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Outline

 Fluid flow through biological protective layers: a comparison of models

Agent-based framework for organism movement in flow

Current/future work

Cylindrical structures create microenvironments for tiny organisms.

Microscale and mesoscale:

- Trichomes (hairs on plants) can reduce evaporative losses and alter the environments for mold, bacteria, etc.
- Transmembrane proteins that form the endothelial glycocalyx shield endothelial cells from blood flow shear and alter the chemical composition of the extracellular environment.

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Macroscale:

- Macrophytes (large aquatic vegetation) cause background flow to be much slower than outside of the layer, reducing erosion and protecting organisms.
- Coral reefs create protective microenvironments that are nutrient rich and home to countless marine organisms.

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Examples of protective layers





Coral Seagrass







Spanish moss Short seagrass Trichomes

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- What is the minimum model necessary to describe the movement of zooplankton around a protective layer?
- Is unbiased Brownian motion + background flow sufficient to model active movement?
- What about advection diffusion instead? What kinds of behavior operate under what circumstances?

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Overall project goals: First part of talk

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ABM

Resolving flows through many (flexible) cylinders across scales is challenging.



We utilize physical and numerical models to describe fully 3D flows:

Physical models:

- Easily incorporate complexity and study organisms directly
- Detailed flow information is difficult to obtain due to optical access.

Numerical models:

- Provides highly resolved temporal and spatial information
- Can require significant computational power.

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Limitations:

- We don't know under what circumstances such models adequately describe the flow
- It is difficult to map a porosity to a particular geometry or volume fraction.

Factors that affect fluid flow through porous layers consisting of cylinder arrays

• The following parameters may be important to the boundary layer....

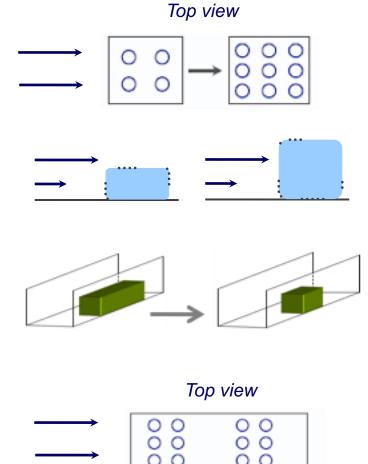
Volume fraction

Cylinder height

Leaf length

Cylinder placement

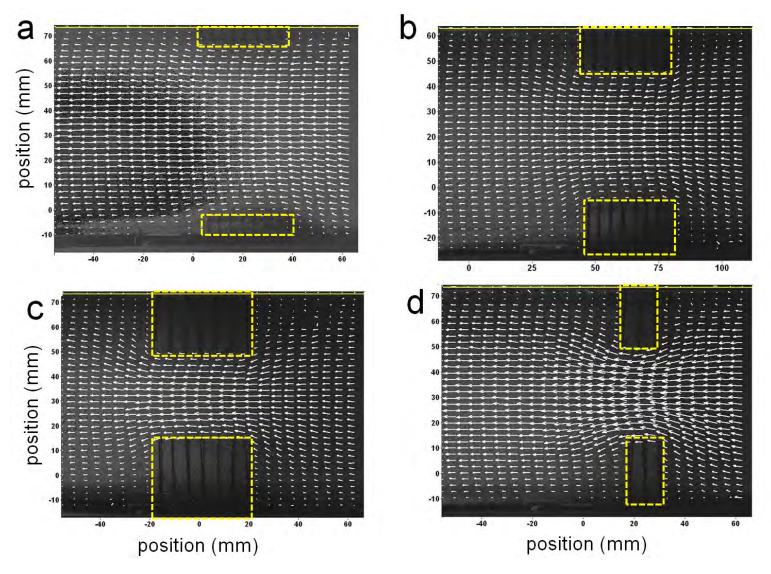
Reynolds number



Examples of protective layers: Scales and Reynolds number

Structure	Diameter	Height	Gap	Re _d
Glycocalyx	10-12 nm	150-400 nm	20 nm	O(-3)
Microvilli	90 nm	$2.5~\mu \mathrm{m}$	165 nm	O(-3)
Aesthetascs	5.69-8.1 μ m	347-648 μ m	10-40 μ m	O(-2)-O(1)
Bristled Wings	0.3-2.5 μ m	25-200 μ m	2-16 μ m	O(-2)
Trichomes	28.1 μ m	96.5 μm	65.6 μm	O(1)
Sea grasses	1 cm	10 cm – 1 m	2-20 cm	O(2)-O(5)
Sea oats	1 cm	1 m	10-40 cm	O(2)-O(5)

Physical model (flow through pins)



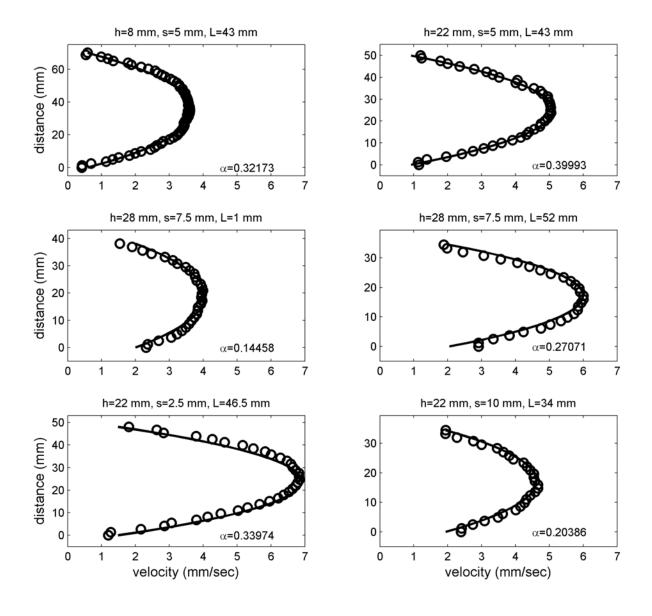
Strickland, Miller, et al. 2017, "Three-Dimensional Low Reynolds Number Flows near Biological Filtering and Protective Layers"

Analytic model

- Treat the cylinders as a porous layer rather than solving the Navier-Stokes equations around each individual component.
- Add a Brinkman term to the N-S equations:
 - α is the inverse of the hydraulic permeability
 - In regions without cylinders, $\alpha(x,y) = 0$.

$$\frac{\partial u}{\partial t} + u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} = -\frac{1}{\rho} \frac{\partial p}{\partial x} + \frac{\mu}{\rho} \left(\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} \right) - \frac{\alpha^2}{\rho} \mu u$$
$$\frac{\partial v}{\partial t} + u \frac{\partial v}{\partial x} + v \frac{\partial v}{\partial y} = -\frac{1}{\rho} \frac{\partial p}{\partial y} + \frac{\mu}{\rho} \left(\frac{\partial^2 v}{\partial x^2} + \frac{\partial^2 v}{\partial y^2} \right) - \frac{\alpha^2}{\rho} \mu v$$

Experiments vs. Brinkman model (best fits)



Numerical simulations of fully resolved flow: Immersed Boundary Method

Navier-Stokes Equations

$$\rho\left(\frac{\partial \mathbf{u}(\mathbf{x},t)}{\partial t} + \mathbf{u}(\mathbf{x},t) \cdot \nabla \mathbf{u}(\mathbf{x},t)\right) = -\nabla p(\mathbf{x},t) + \mu \Delta \mathbf{u}(\mathbf{x},t) + \mathbf{f}(\mathbf{x},t)$$

$$\nabla \cdot \mathbf{u}(\mathbf{x},t) = 0$$

Force applied to fluid

$$\mathbf{F}(r,t) = \mathbf{F}_{\text{targ}}(r,t) + \mathbf{F}_{\text{beam}}(r,t) + \mathbf{F}_{\text{str}}(r,t)$$

Force spreading

$$\mathbf{f}(\mathbf{x},t) = \int \mathbf{F}(r,t) \,\delta(\mathbf{x} - \mathbf{X}(r,t)) dr$$

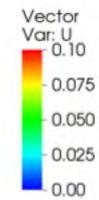
Velocity interpolation

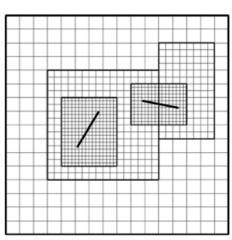
$$\frac{\partial \mathbf{X}(r,t)}{\partial t} = \mathbf{U}(\mathbf{X}(r,t)) = \int \mathbf{u}(\mathbf{x},t) \delta(\mathbf{x} - \mathbf{X}(r,t)) d\mathbf{x}$$

- 1. Solve the equations of fluid motion.
- 2. Move the boundary at the local fluid velocity.
- 3. Determine the force applied to the fluid as the deformation of the boundary and an external force.
- 4. Convert from Lagrangian to Eulerian variables (spread force to fluid).

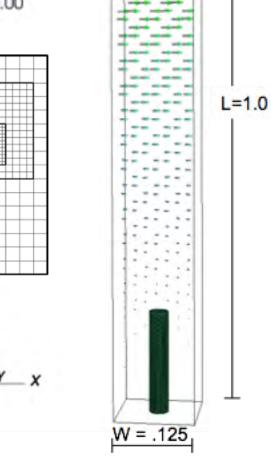
Numerical set-up

- 1.Background shear flow that is periodic in x- and y-directions.
- 2. Nearly rigid cylinders placed on bottom of domain.
- 3.An adaptive and parallelized version of the immersed boundary method is used (IBAMR).

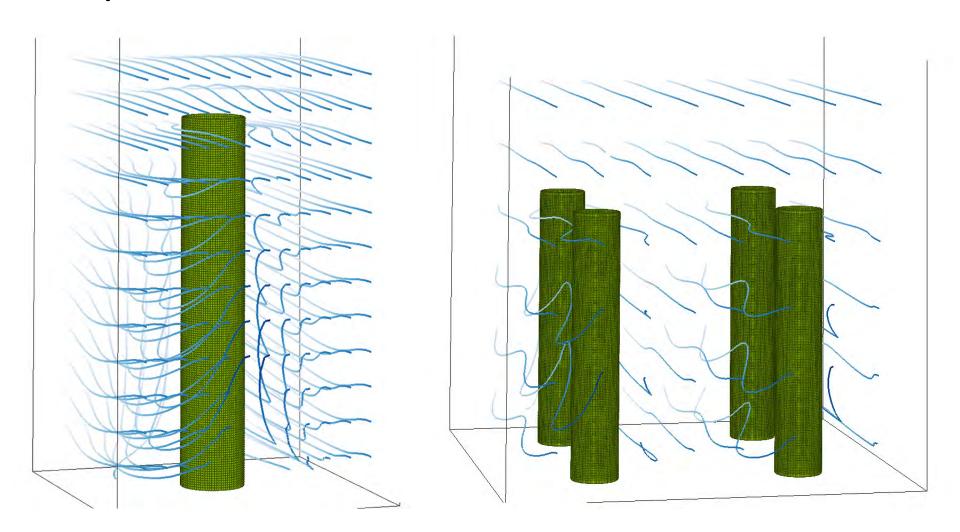




Griffith, B.E. "IBAMR: An adaptive and distributed-memory parallel implementation of the immersed boundary method." http://ibamr.googlecode.com



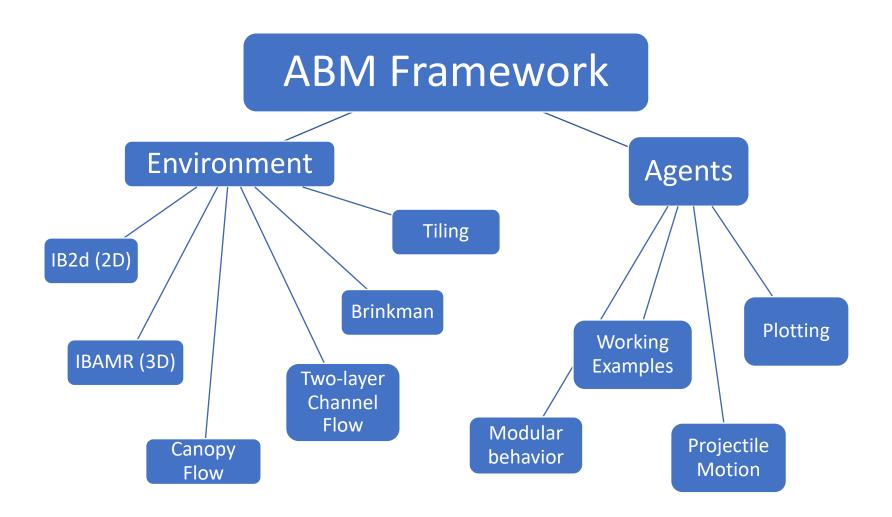
Avg. numerical flow is well approximated by Brinkman... but small eddies can exist.

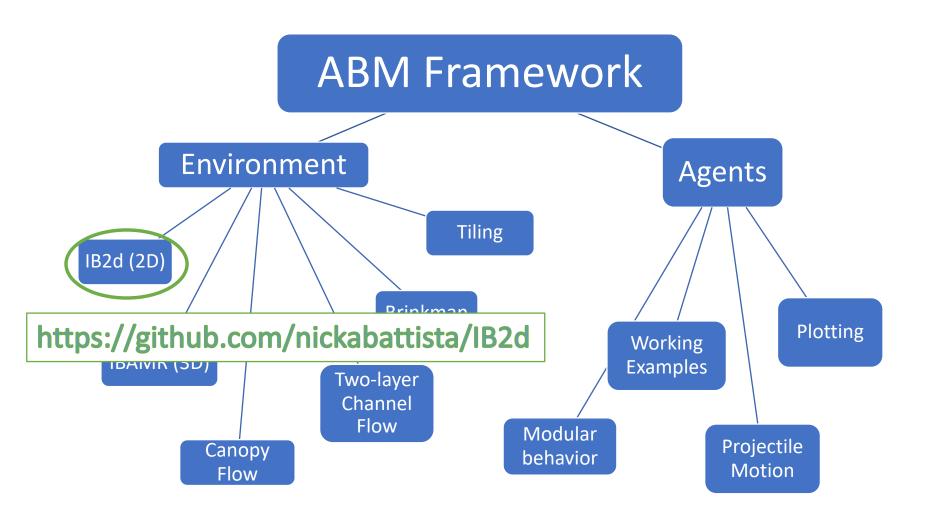


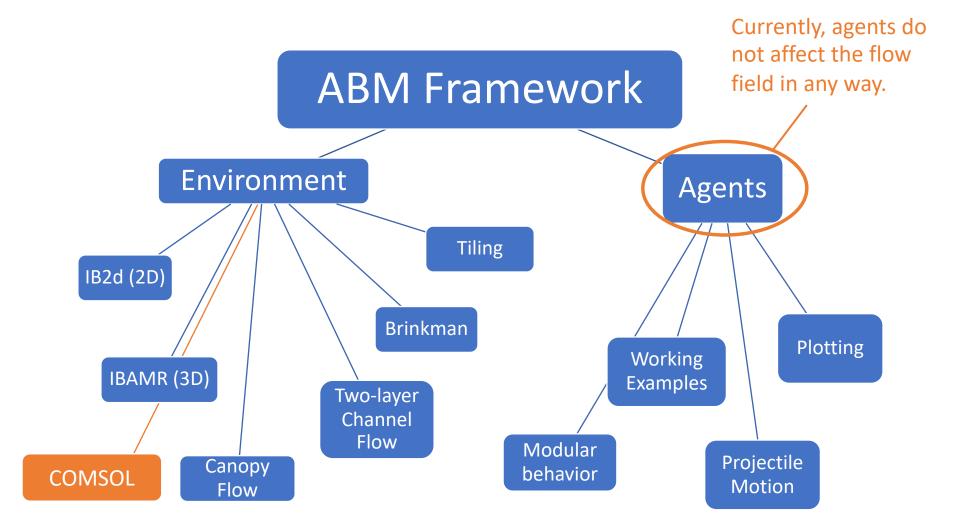
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Project goals: What can an agent based model tell us about zooplankton?

- Are homogenized steady flow fields sufficient to describe the fluid (e.g. Brinkman model), or are full 3D and/or time varying flows necessary?
- What is the minimum model necessary to describe the movement of zooplankton into and out of a protective layer?
- Is Brownian motion added to the background flow sufficient to model active movement, or is it necessary to add behavior?
- Can behavior be modeled as biased diffusion?

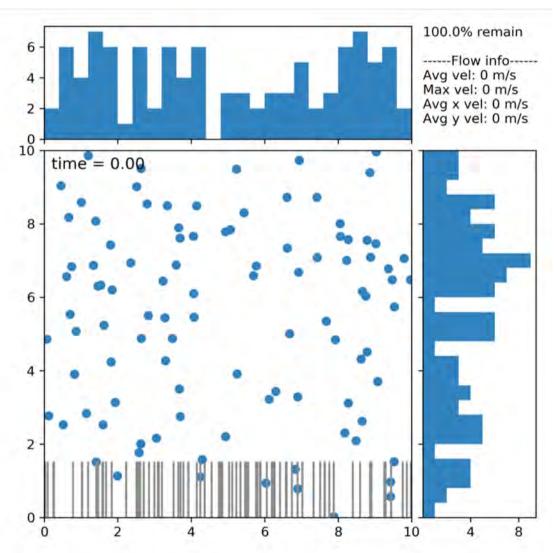






```
#! /usr/bin/env python3
from sys import platform
if platform == 'darwin': # OSX backend does not support blitting
    import matplotlib
    matplotlib.use('TkAgg')
import numpy as np
import sys
sys.path.append('...')
import framework
envir = framework.environment(Lz=10, rho=1000, mu=1000)
U=0.1*np.array(list(range(0,5))+list(range(5,-5,-1))+list(range(-5,8,3)))
envir.set_brinkman_flow(alpha=66, a=1.5, res=101, U=U,
                        dpdx=np.ones(20)*0.22306, tspan=[0, 20])
envir.add_swarm()
s = envir.swarms[0]
print('Moving swarm...')
for ii in range(240):
    s.move(0.1)
#s.plot_all('ex_3d.mp4', fps=20)
s.plot_all()
```

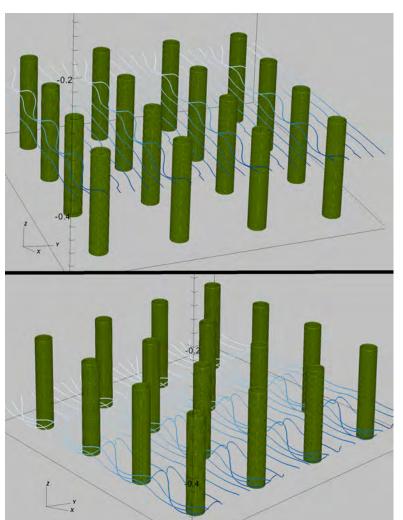
- Written in Python
- Interfaces with 2D or 3D (time varying) flow data
- Some 1D analytical flow fields included
- 2D/3D plotting
- Relatively easy to add custom behavior and response to flow gradients



Example: 1D Brinkman flow

- 1.5 m homogenous porous layer
- Time varying flow specified at the top of the domain
- Tracer particles with jitter
- Histograms show relative x/y abundance

Example ABM simulation: IBAMR flow through cylinder array



Fluid specifications:

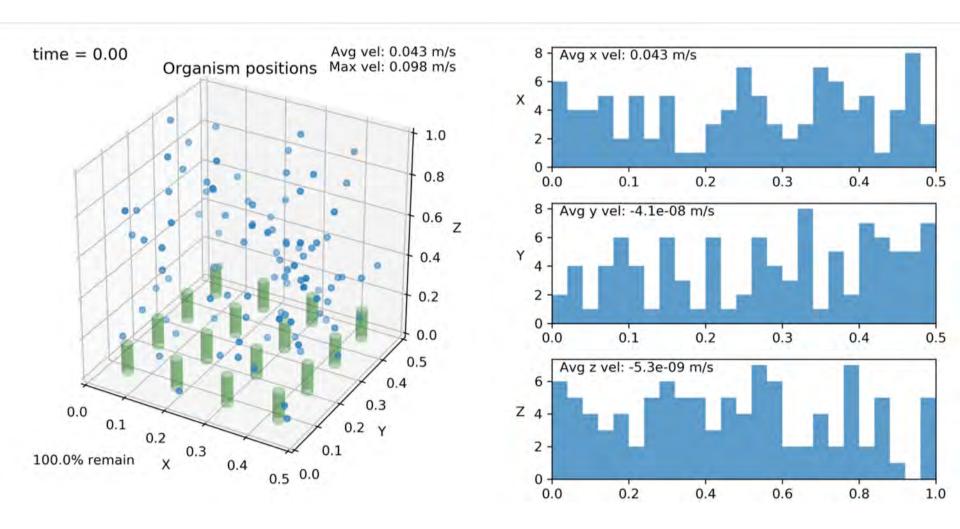
- 0.15 m tall cylinders in 0.5x0.5x1 meter domain
- Re_d 10
- Cylinders do not inhibit movement

Agent behavior:

- Agents are massless point particles
- Unbiased random walk with std of 1 cm
- Agents are advected by the flow field
- Agents are initialized at uniformly random positions

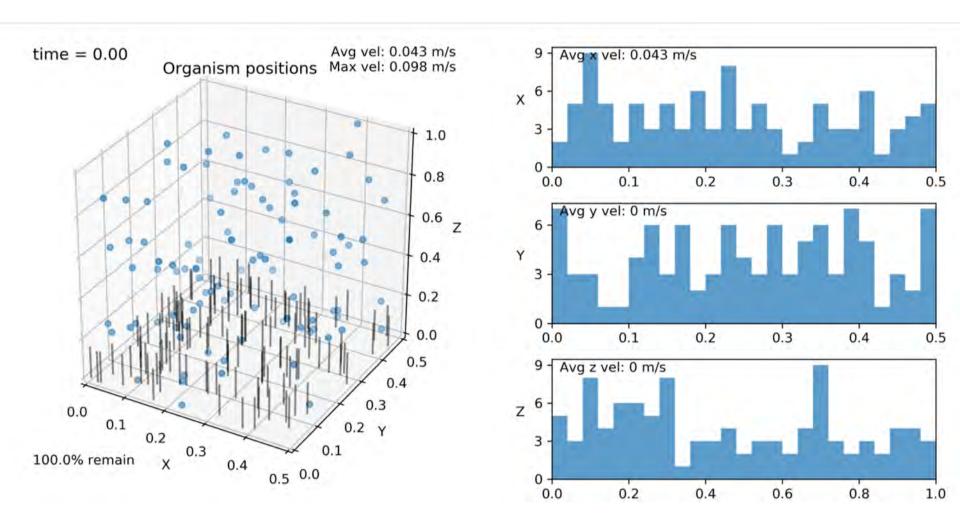
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ABM simulation: IBAMR flow through cylinder array



https://github.com/mountaindust/Planktos

ABM simulation: Brinkman flow through similar porous region



https://github.com/mountaindust/Planktos

Current work

Obtain data from an idealized experiment: brine shrimp injected between cylinders in a flow field

- Measure flow fields through a protective layer using PIV and physical models
- Add brine shrimp to this flow and measure their distributions over time

Challenges:

- Illuminate and keep in focus a large section of the flow field
- Use diffuse light since brine shrimp are phototactic

Current work

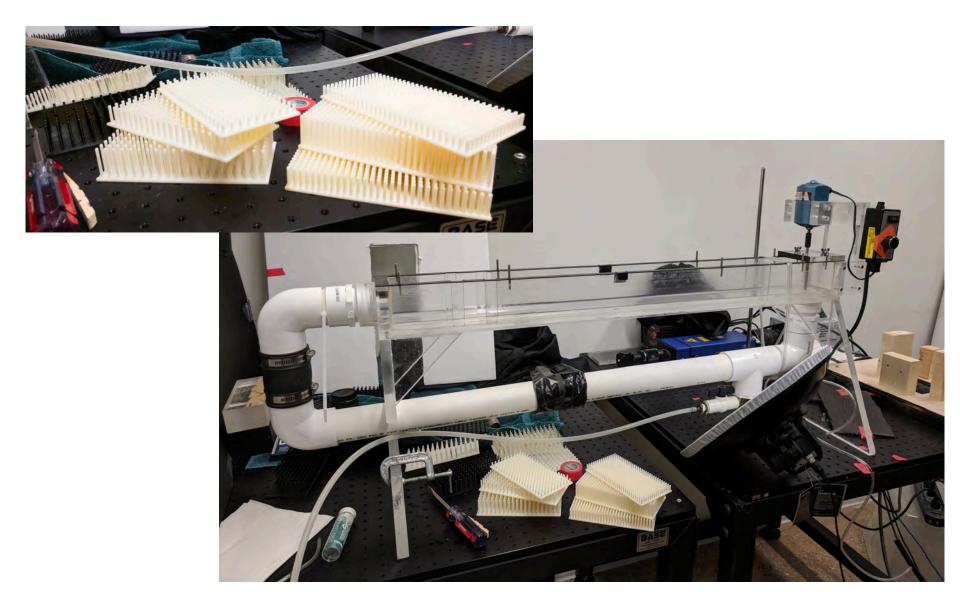
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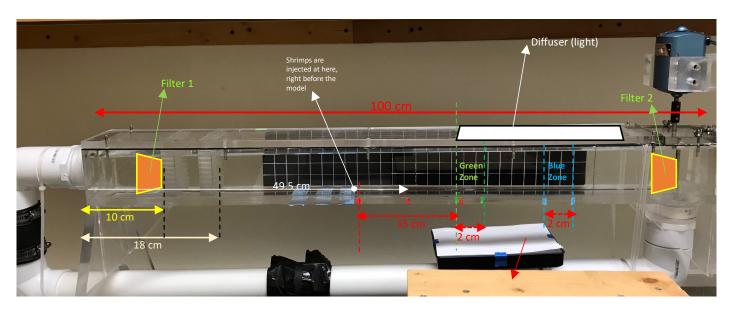
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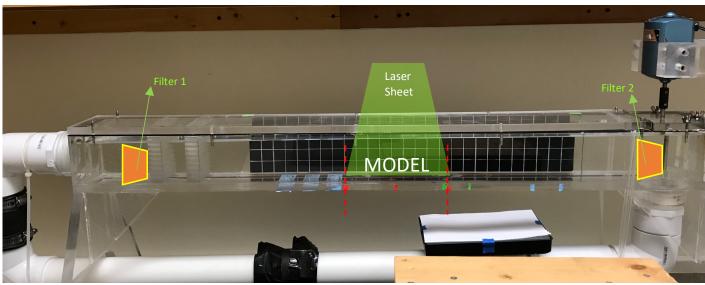
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Experimental flow through cylinder arrays

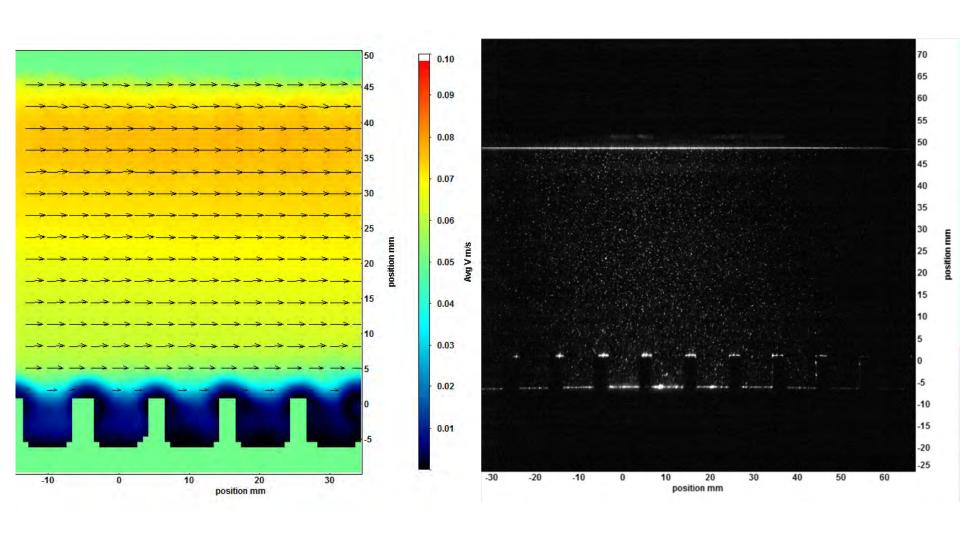


Experimental flow through cylinder arrays

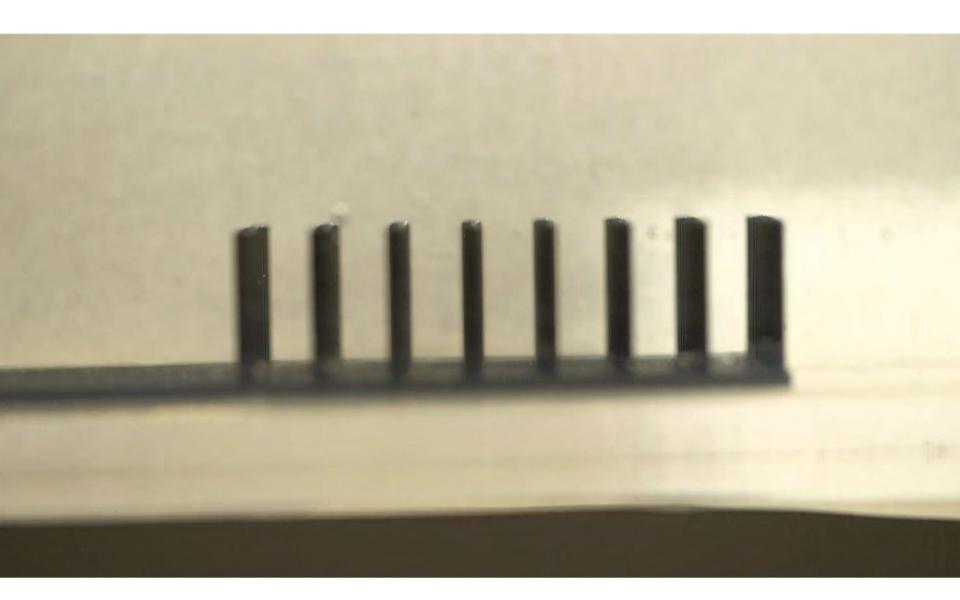




Experimental flow through cylinder arrays



Brine shrimp movement



Current work

Model the collective behavior:

- Fully 3D fluid-structure interaction data from IBAMR/COMSOL.
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- Question: what is the minimal behavior necessary to capture the experimental distribution?

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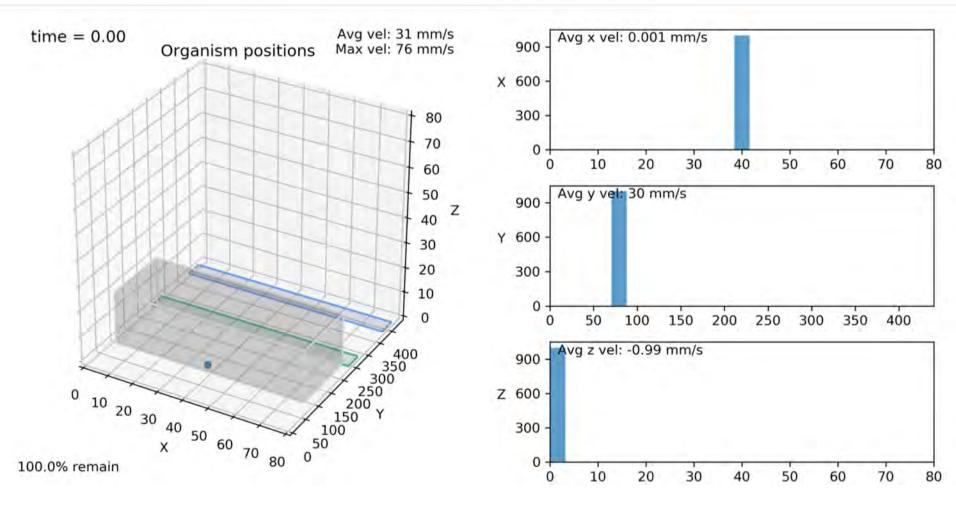
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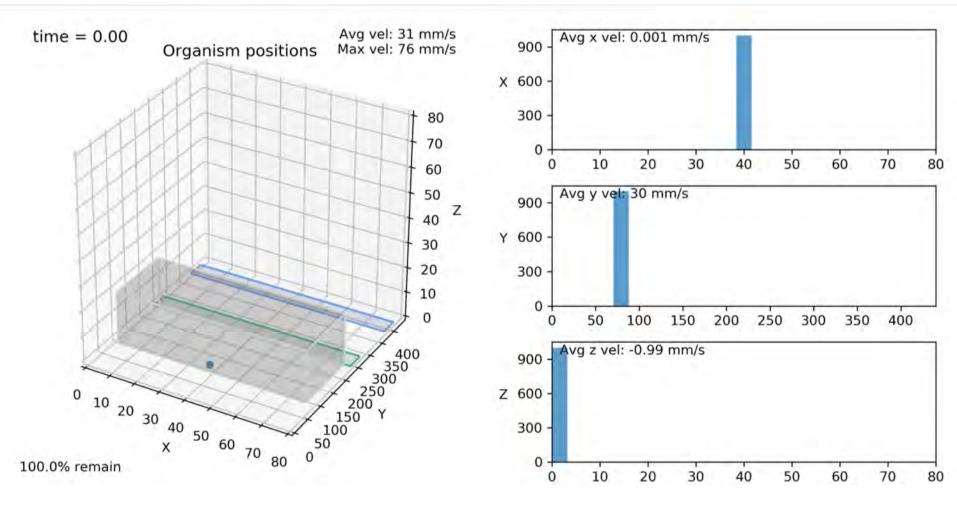
Example: ABM simple jitter simulation within IBAMR flow



Diffusion coeff. based on Kohler, Swank, Haefner, Powell (2010)

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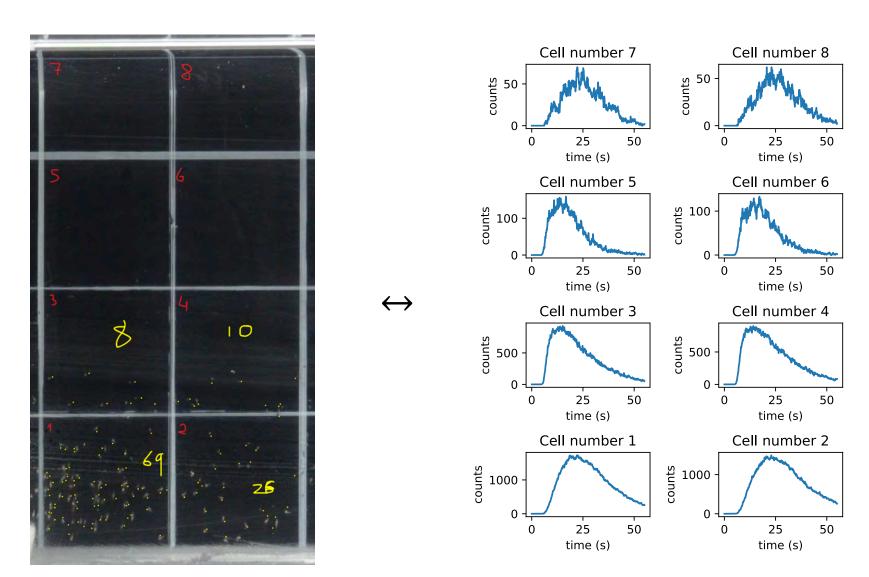
Example: ABM simulation within IBAMR flow with velocity gradient following



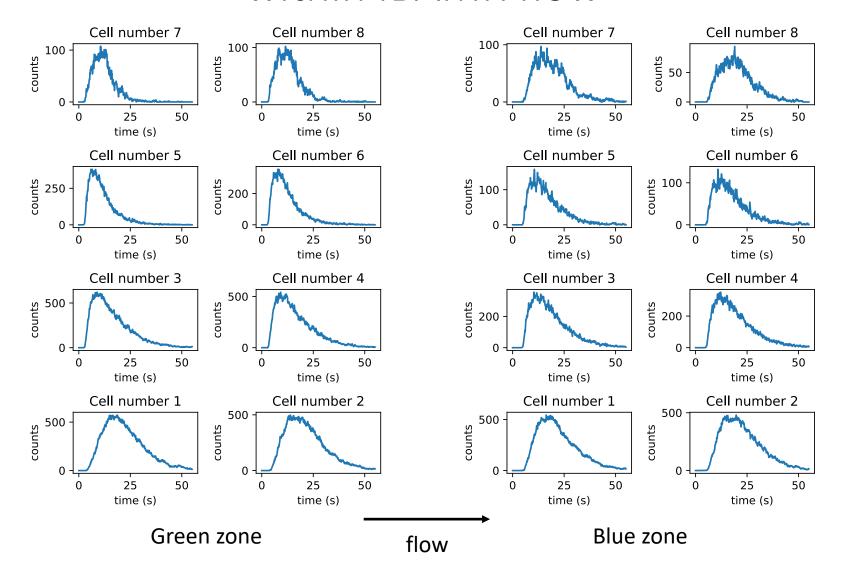
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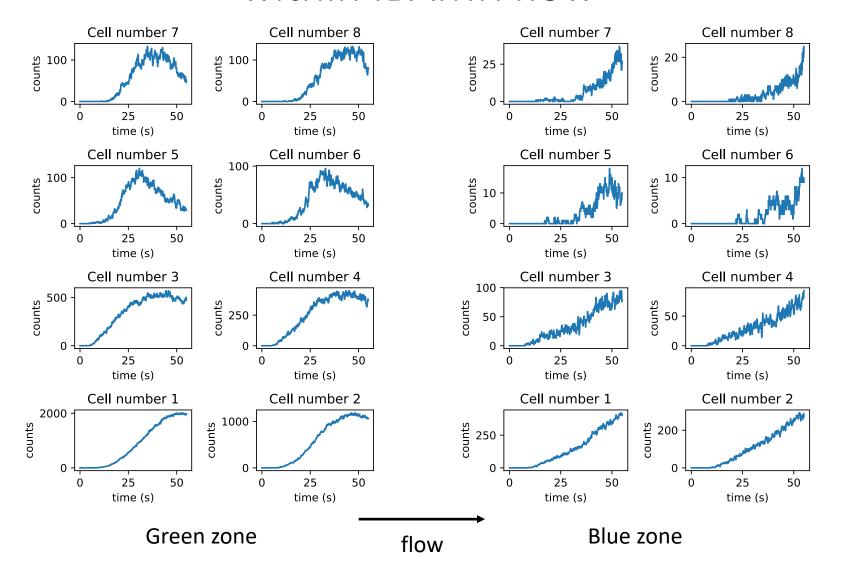
Next step: Compare counts over time in aggregate and in sections



Example: ABM simple jitter simulation within IBAMR flow



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- Compare numerical results to experimental results (need more computationally stable FSI data: COMSOL)
- Collect data on diffusion coefficients with conditions that better match our scenario
- Fine tune agent behavior. Does an attractive stimulus change results (e.g. light)?
- Specify a population-level, minimal analytic model. What is an efficient way to do model selection?

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Thank you for your attention! www.christopherstrickland.info

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